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amplifier angle applied approximation assumed asymptotes becomes block diagram Bode plot branches called Chapter characteristic equation closed-loop coefficients compensated system compensator complex components computed condition Consider constant contour control system corresponding curve damping defined derivative describing desired ...

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Focuses on the first control systems course of BTEch, JNTU, this book helps the student prepare for further studies in modern control system design. It offers a profusion of examples on various aspects of study.

Key Features: Examples have been provided to maintain the balance between different disciplines of engineering. Robust control, Robotic control and Robotic modeling introduced. PID learning procedures illustrated. Updation of obsolete technology with examples. State variable formulation and design simplified. Digital control, both classical and modern approaches, covered in depth. Chapters on Nonlinear Systems, Adaptive, Fuzzy Logic and Neural Network Control included. An appendix in MATLAB with examples from time and frequency domain analysis and design included. About the Book: The book provides an integrated treatment of continuous and discrete-time systems for two courses at undergraduate level or one course at postgraduate level. The stress is on the interdisciplinary nature of subject and examples have been drawn from various engineering disciplines to illustrate the basic system concepts. A strong emphasis is laid on modeling of practical systems involving hardware: control components of a wide variety are comprehensively covered. Time and frequency domain techniques of analysis and design of control systems have been exhaustively treated and their interrelationship established. Adequate breadth and depth is made available for second course. The coverage includes digital control systems: analysis, stability and classical design; state variables for both continuous and discrete-time systems; observers and pole-placement design; Liapunov stability; optimal control; and recent advances in control systems: adaptive control, fuzzy logic control, neural network control.

This hallmark text on Power System Engineering provides the readers a comprehensive account of all key concepts in the field. The book includes latest technology developments and talks about some crucial areas of Power system, such as Transmission & Distribution, Analysis & Stability, and Protection & Switchgear. With its rich content, it caters to the requirements of students, instructors, and professionals.

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Basic Electrical and Electronics Engineering is a renowned book that attempts to provide a thorough coverage on basics of electrical and electronics engineering in a single volume. This second edition of the book has been carefully revised to include important topics like domestic wiring, electrical installations, instrument transformers, battery, etc. Written in a lucid manner, it enables the learners to apply the basic concepts of electrical and electronics engineering for multi-disciplinary tasks and lays the foundation for higher level courses. Rich pool of problems and appendices enhance the utility of the book and make it a lasting resource for students and instructors of all branches of engineering.

About the book... The book provides an integrated treatment of continuous-time and discrete-time systems for two courses at postgraduate level, or one course at undergraduate and one course at postgraduate level. It covers mainly two areas of modern control theory, namely: system theory, and multivariable and optimal control. The coverage of the former is quite exhaustive while that of latter is adequate with significant provision of the necessary topics that enables a research student to comprehend various technical papers. The stress is on interdisciplinary nature of the subject. Practical control problems from various engineering disciplines have been drawn to illustrate the potential concepts. Most of the theoretical results have been presented in a manner suitable for digital computer programming along with the necessary algorithms for numerical computations.

This comprehensive text on control systems is designed for undergraduate students pursuing courses in electronics and communication engineering, electrical and electronics engineering, telecommunication engineering, electronics and instrumentation engineering, mechanical engineering, and biomedical engineering. Appropriate for self-study, the book will also be useful for AMIE and IETE students. Written in a student-friendly readable manner, the book, now in its Second Edition, explains the basic fundamentals and concepts of control systems in a clearly understandable form. It is a balanced survey of theory aimed to provide the students with an in-depth insight into system behaviour and control of continuous-time control systems. All the solved and unsolved problems in this book are classroom tested, designed to illustrate the topics in a clear and thorough way. NEW TO THIS EDITION: One new chapter on Digital control systems • Complete answers with Figures • Root locus plots and Nyquist plots redrawn as per MATLAB output • MATLAB programs at the end of each chapter • Glossary at the end of chapters KEY FEATURES: Includes several fully worked-out examples to help students master the concepts involved. • Provides short questions with answers at the end of each chapter to help students prepare for exams confidently • Offers fill in the blanks and objective type questions with answers at the end of each chapter to quiz students on key learning points • Gives chapter-end review questions and problems to assist students in reinforcing their knowledge. Solution Manual is available for adopting faculty.

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